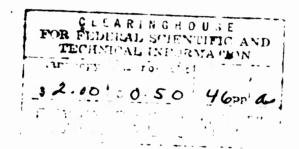


ENGINEERING GRAPHICS SEMINAR

FOUR-DIMENSIONAL DESCRIPTIVE GEOMETRY METRIC PROBLEMS: ANGLES - DESCRIPTIVE SOLUTION

C. Ernesto S. Lindgren Visiting Research Engineer United States Steel Corporation

May 1965



Anothive Copy

TECHNICAL SEMINAR SERIES

Special Report No. 6

Department of Graphics and Engineering Drawing School of Engineering and Applied Science Princeton University

(C) 1965 C. Ernesto S. Lindgren

()

ABSTRACT

The paper presents the descriptive geometry solution of the determination of the angles between geometric elements in a four-dimensional euclidean space.

Incorporated in these solutions are the discussions of some problems of intersections between two geometric elements. These are: intersection of a line and a plane, belonging to the same 3-D space; intersection of two planes belonging to distinct 3-D spaces; intersection of a line and a 3-D space; intersection of a plane and a 3-D space.

Problem No. 1

"To determine the true value of the angle of two lines".

Preliminary discussion: if the two lines are nonconcurrent, through a point of one draw a line parallel to the other and determine the angle of the two concurrent lines.

Solution

1434.5

Consider a 3-D space that belongs to the plane determined by the two concurrent lines, apply a rotation of the 3-D space 1) until it is superimposed on one of the 3-D spaces of the 4-D system of reference, and use a three-dimensional method of descriptive geometry to determine the true value of the angle.

To determine a 3-D space that belongs to the plane (abc) find the points of intersection of plane (abc) with the planes Π_1 , Π_2 , Π_3 of the 4-D system of reference. (Figure 2)

¹⁾ See the author's Special Report No. 4, Engineering Graphics Seminar, Department of Graphics and Engineering Drawing, Princeton University, March, 1965.

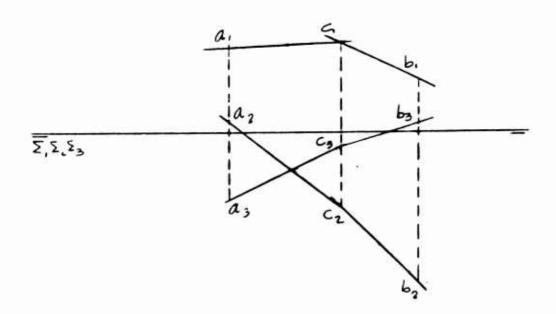


Figure 1

Next. using \mathcal{T}_1 . \mathcal{T}_2 , \mathcal{T}_3 as axes of reference, determine the position of (a), (b), and (c). See pictorial view in Figure 3 and constructions in the orthographic projection in Figure 4.

To determine the superimposition of 3-D space T on the 3-D space Σ_3 of the 4-D system of reference, consult our Special Report No. 4^2). The graphical constructions are shown in Figures 5, 6, and 7.

²⁾ Engineering Graphics Seminar, Technical Seminar Series, Department of Graphics and Engineering Drawing, Princeton University.

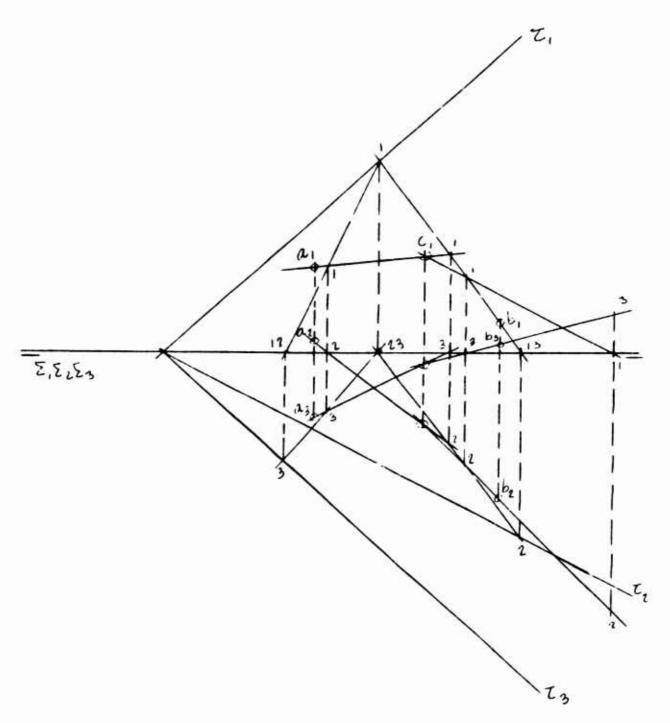


Figure 2

As seen in Figure 7, the line (ob") represents the trace \mathcal{Z}_3 of the 3-D space \mathcal{T} . We shall proceed by determining the positions of (a') and (c') on that line (Figure 8). The true lengths of (oa') and (oc') are obtained from Figure 5.

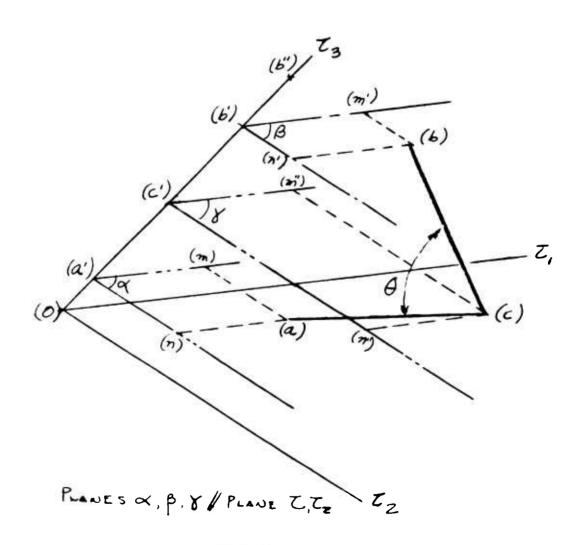


Figure 3

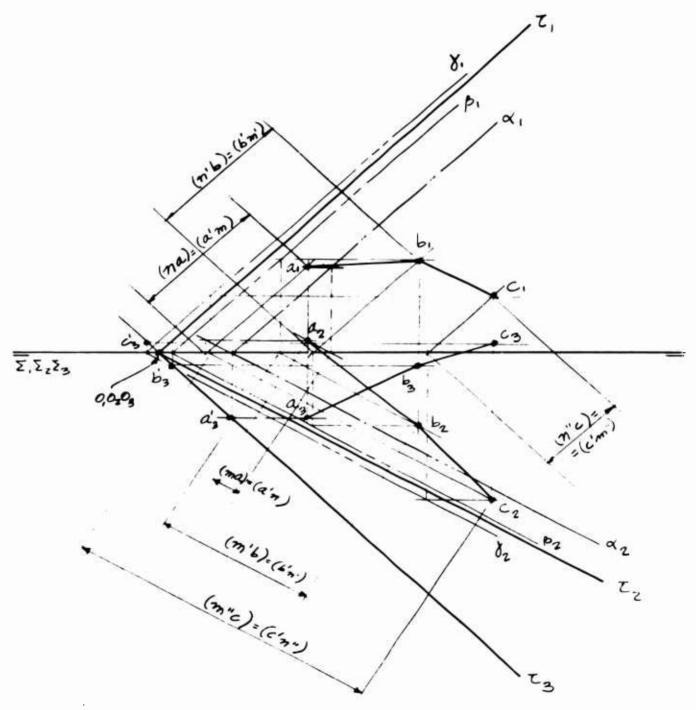


Figure 4

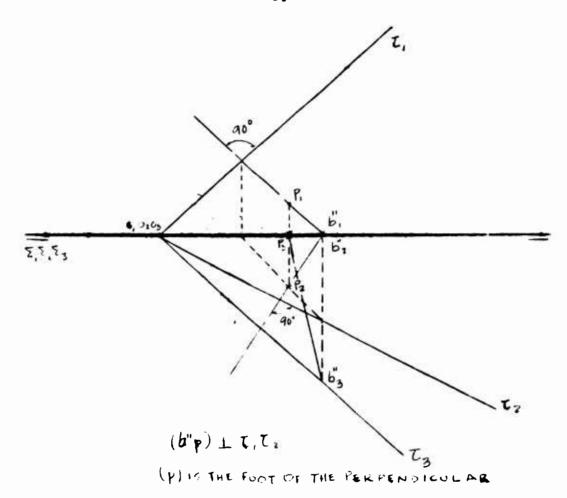


Figure 5

Next, draw (a'm), (b'm'), (c'm") parallel to \mathcal{T}_1 , (a'n), (b'n'), (c'n") parallel to \mathcal{T}_2 , marking its respective lengths obtained from Figure 5. Then, through (m) and (n) draw parallels to \mathcal{T}_2 and \mathcal{T}_1 , respectively, to determine (a). Use similar procedures to obtain (b) and (c), working with points (m'), (n'), (m"), and (n"). Figure 9.

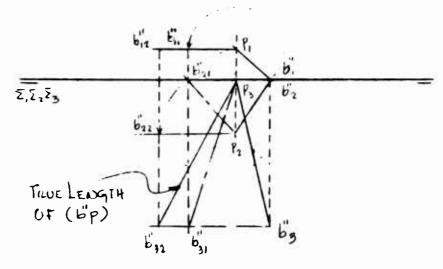


Figure 6

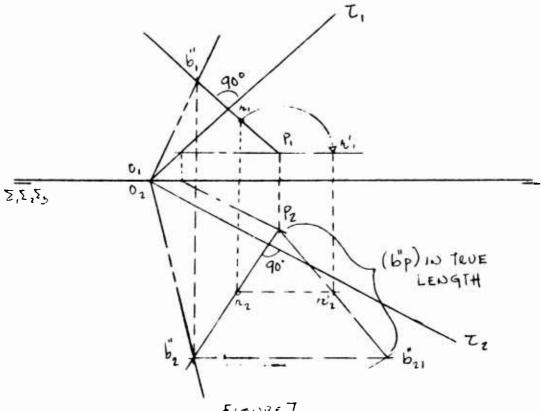


FIGURE 7

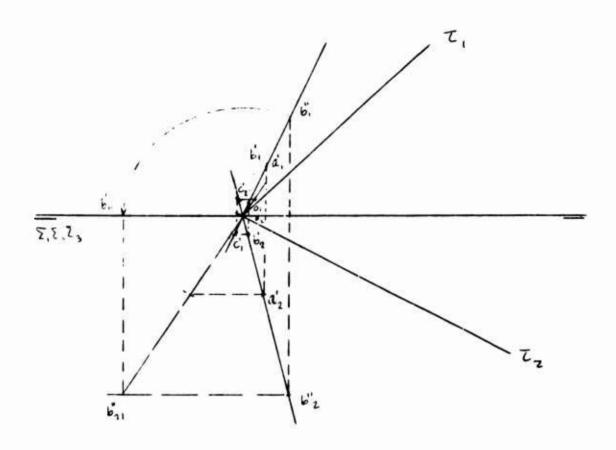


Figure 8

Thus, we obtained the projections of the three points (a), (b), (c), of the 3-D space \mathbb{T} , when superimposed on the 3-D space Σ_3 . To determine the true value of the angle (a\$\hat{c}\$\dot{b}\$), use a method of the three-dimensional descriptive geometry. (Figure 10).

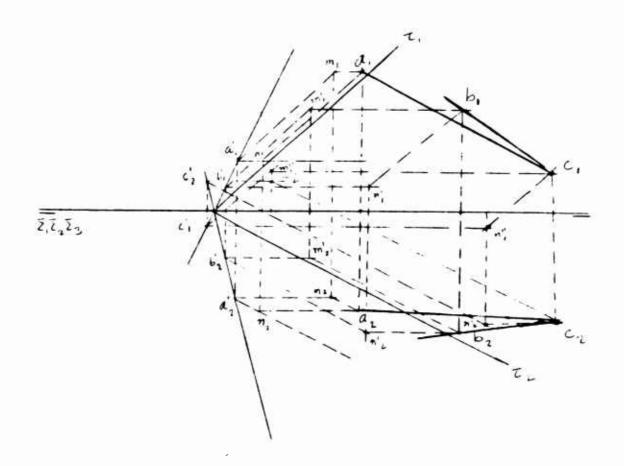


Figure 9

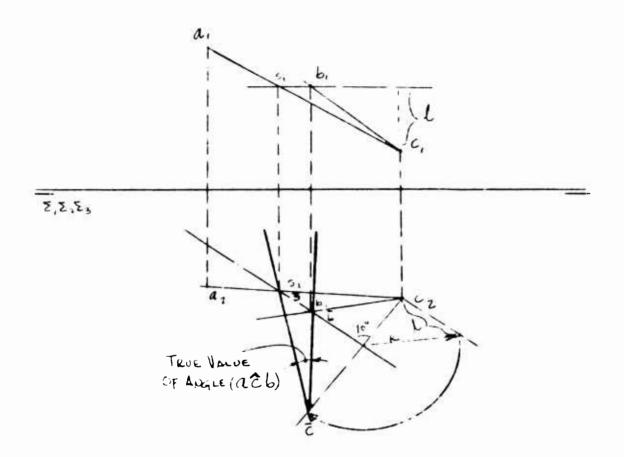


Figure 10

Problem No. 2

"To determine the true value of the angle of a line and a plane".

Preliminary discussion: if the line and the plane are non-concurrent, (belonging to two distinct 3-D spaces),

through a point of the plane draw a line parallel to the given one and determine its angle with the plane.

Solution |

The angle of a line with a plane is equal to the angle of the line with its orthogonal projection on the plane.

Thus we should find the point (a), intersection of the line and the plane and through a point (b), of the line draw a perpendicular to the plane and determine its foot, point (p). The angle (bap) is the angle of (ab) with the plane. (Figure 11).

(ab)
$$x \propto = (a)$$
 $(bap) = (ab), \propto$
(bp) $\pm \propto$
(cb), (sp) = (ab), \propto
Where (cs) $\pm \propto$

Figure 11

The general proposition of the problem gives a line (b'c') and a plane \propto . In Figure 12, the plane \propto is given by two concurrent lines (R) and (T).

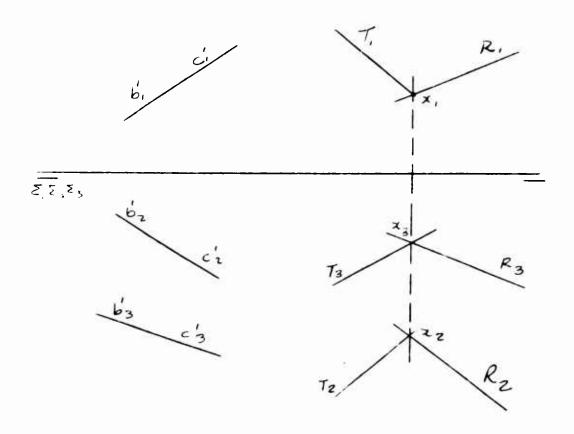


Figure 12

Without investigating if they belong to the same 3-D space, take a point (a) in (R) and draw (ab) parallel to (b'c'). (Figure 13).

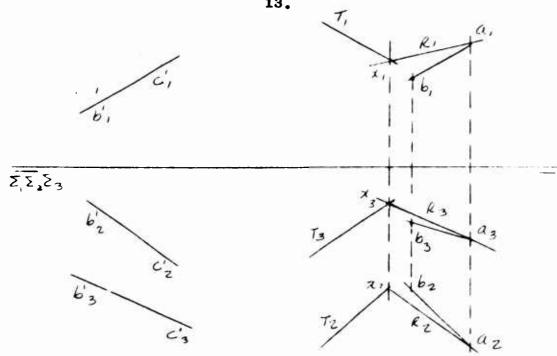


Figure 13

Consider the 3-D space (R, T - b) to proceed with the solution.

Since through (b) we have to draw perpendicular to plane (R, T) $\equiv \alpha$, it will be necessary to apply a descriptive method so that we may properly operate within the 3-D space (R, T - b). The objective should be to place the plane \propto parallel to one of the 3-D spaces of the 4-D system of reference, as indicated in Figure 14. Here, the plane lpha is parallel to Σ_3 and belongs to the 3-D space T.

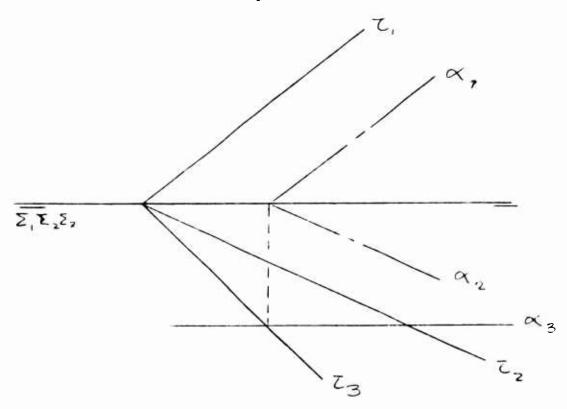


Figure 14

The graphical constructions pertinent to the application of the descriptive method are outlined in other papers³⁾ and we shall not repeat them here.

Therefore, let us admit the 3-D space $\forall x \in (R, T - b)$ of Figure 15, given by its traces, and the plane α and point (b) belonging to it. In the plane α we consider

³⁾ Descriptive Geometry of Four Dimensions, Engineering Graphics Seminar, Technical Seminar Series, Report No. 9, Department of Graphics and Engineering Drawing, Princeton University, December 5, 1963.



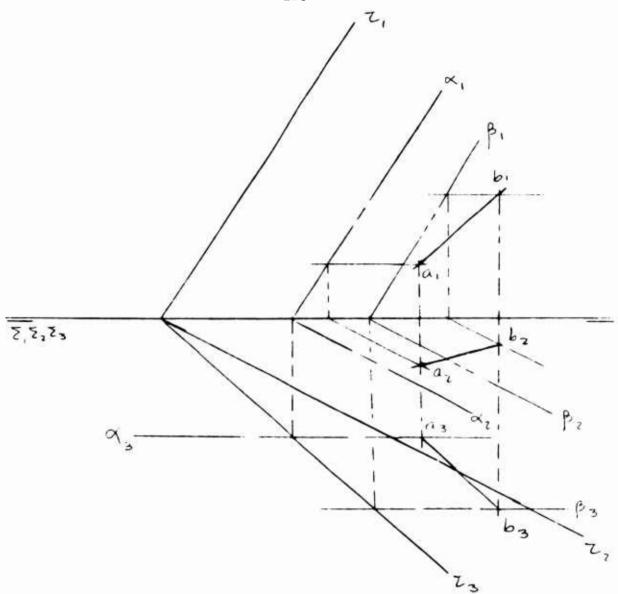


Figure 15

23.5

Billian Commence

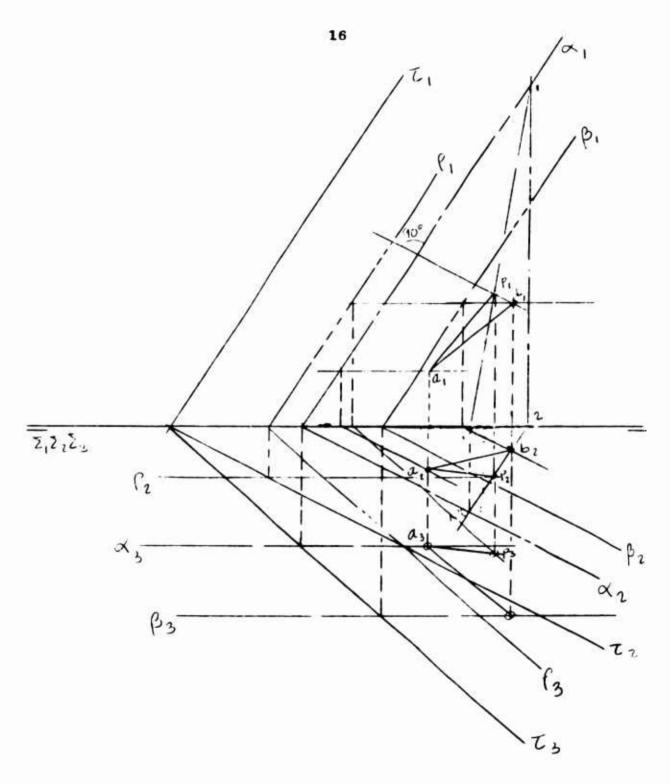


Figure 16

the point (a), and we shall determine the angle that (ab) forms with α .

Through (b) draw the perpendicular to \propto and determine the foot (p) of the perpendicular. (Figure 16).

To determine the angle of (ab) and (bp) apply the solution outlined for Problem No. 1.

Problem No. 3

"To determine the true value of the angle of two planes that belong to the same 3-D space".

Solution

Let α and β be the given planes, intersecting along a line (xy). Through (a) of (xy) pass a plane γ , perpendicular to (xy) and determine $\alpha \times \gamma = (ab)$ and $\beta \times \gamma = (ac)$. The true value of the angle (bac) is the solution sought. (Figure 17).

In Figure 18, the plane \propto is given parallel to the 3-D space \geq and the plane β is given by the points (m), (n), (p). The intersection of the two planes is the line (xy).

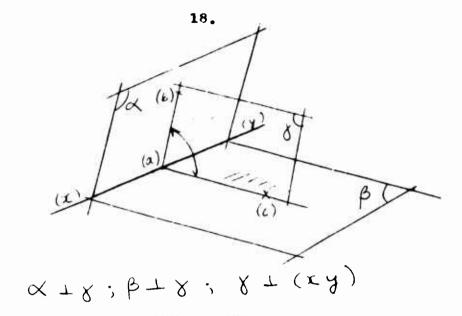
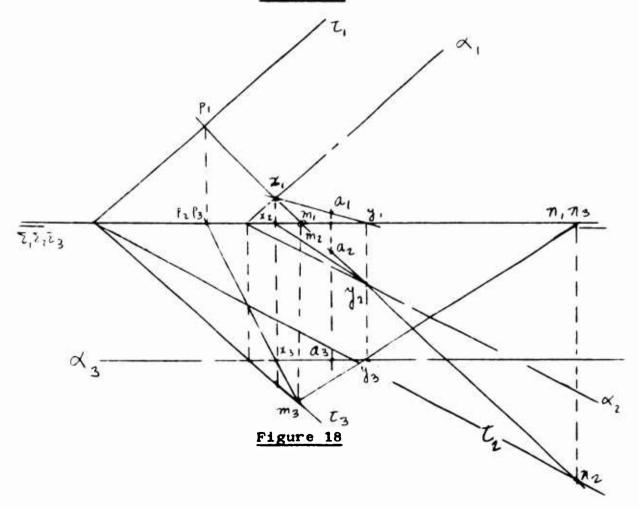


Figure 17



To determine (ab) perpendicular to (xy) in plane \propto , apply rotation to the plane, about \propto 2, until superimposition on plane π 2 of the 4-D system of reference. See Figure 19.

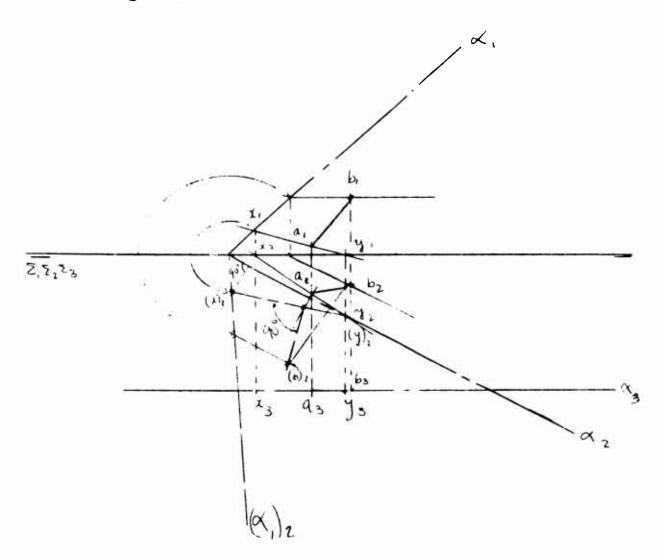


Figure 19

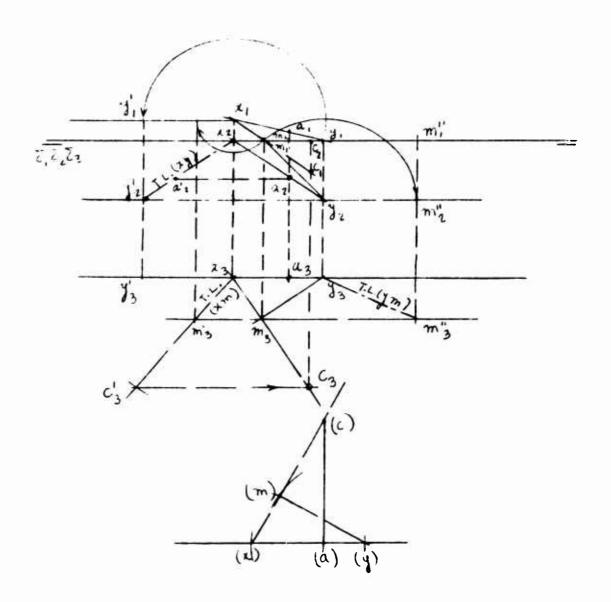


Figure 20

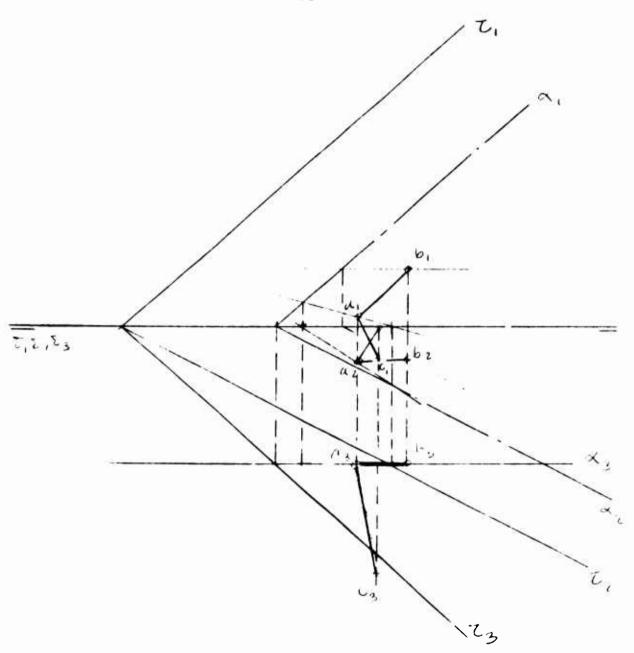


Figure 21

To determine (bc) perpendicular to (xy), in plane $\beta \equiv (mnp)$, apply changes in the 3-D spaces of reference, until β belongs to one of them, or determine the true lengths of the sides of the triangle (xym), draw (ac) perpendicular to (xy), and determine the projections of (c). See Figure 20.

Thus, we obtained the sides (ab) and (ac) of the plane angle that measures the angle of the two planes \propto and β (Figure 21).

Apply the solution of Problem No. 1 to obtain the true value of the angle.

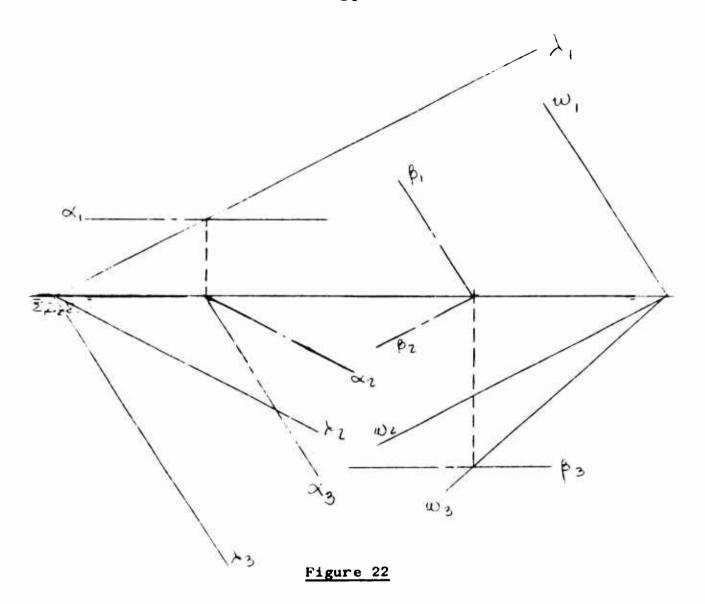
Problem No. 4

"To determine the true value of the angles of two planes belonging to distinct 3-D spaces".

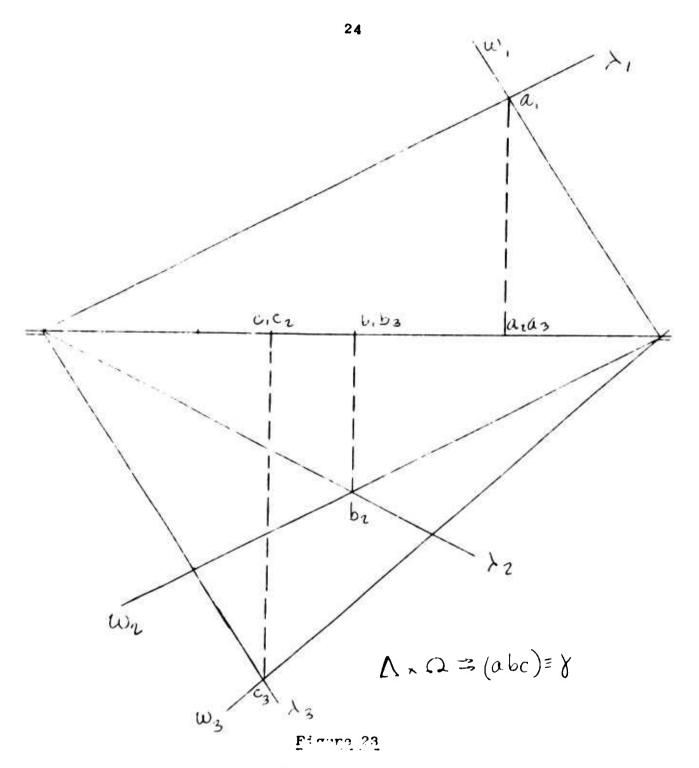
Solution

Let \triangle and Ω be two given 3-D spaces, and α a plane of \triangle , and β a plane of Ω . (Figure 22).

First determine the plane of intersection of the two 3-D spaces. That is plane (Cbc) = // , Figure 23.



Next, determine the intersection of planes (abc) and \varnothing , in 3-D space \bigwedge . That is line (mn), Figure 24.



Next, determine the full reaction of planes (ahc) and β , in a 3-D space Ω . That, is line (op), Figure 25.

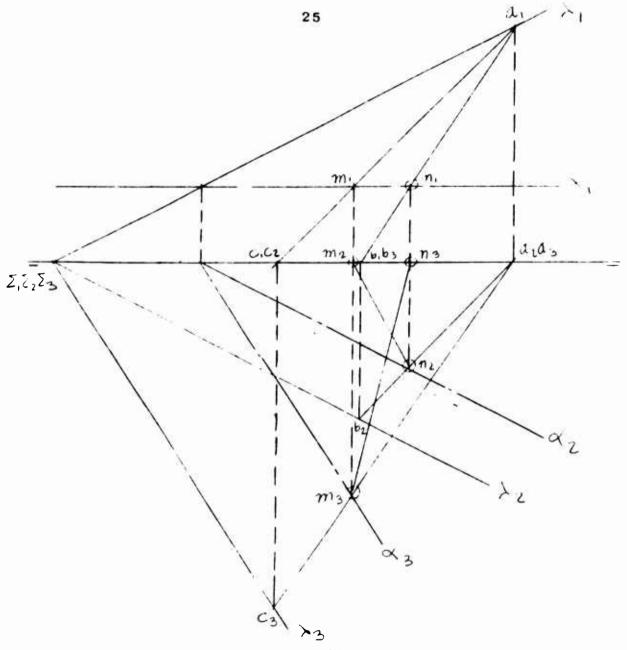


Figure 24

Finally, determine the intersection of lines (mn) and (op), point (s), in plane (abc). (Figure 26). The point (s) is the intersection of planes \propto and β .

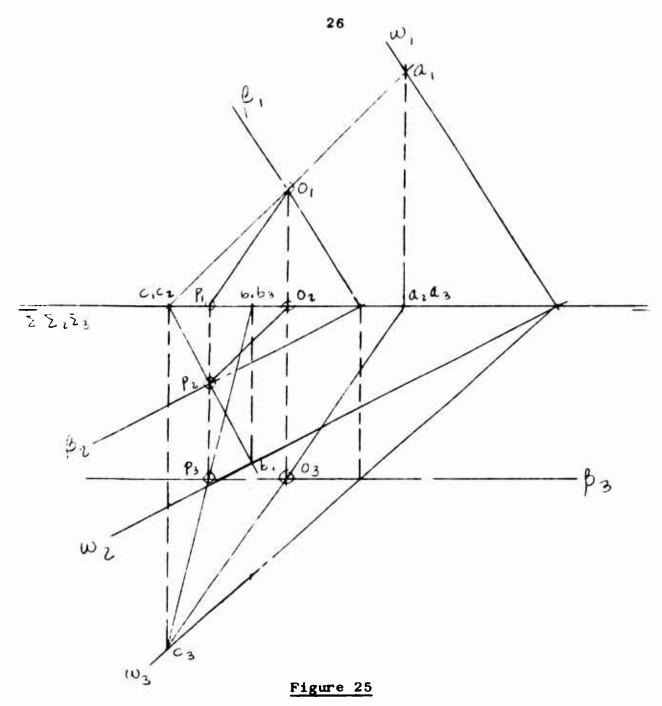


Figure 27 shows all the constructions just outlined.

The point (s) is the vertice of the two minimal angles between the two planes.

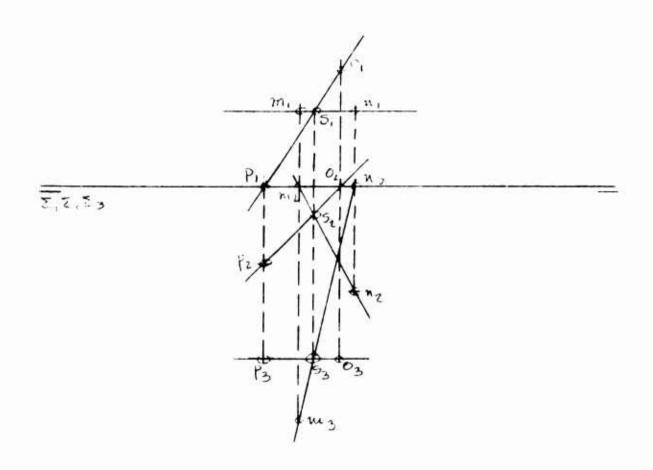
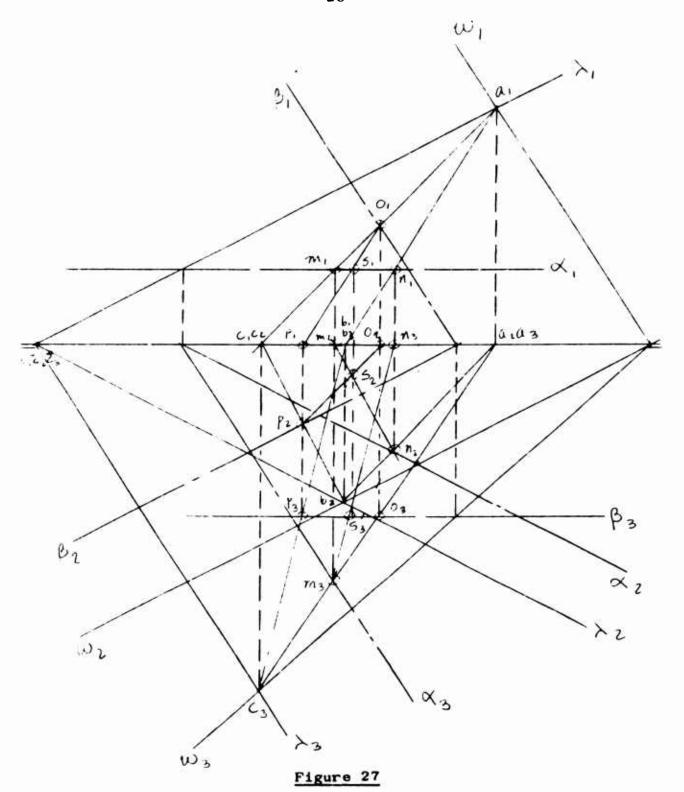


Figure 26

To determine the sides of the first angle, through (s) draw (st) perpendicular to plane α , in 3-D space Λ , and (sv) perpendicular to plane β , in 3-D space Ω . (Figure 28).



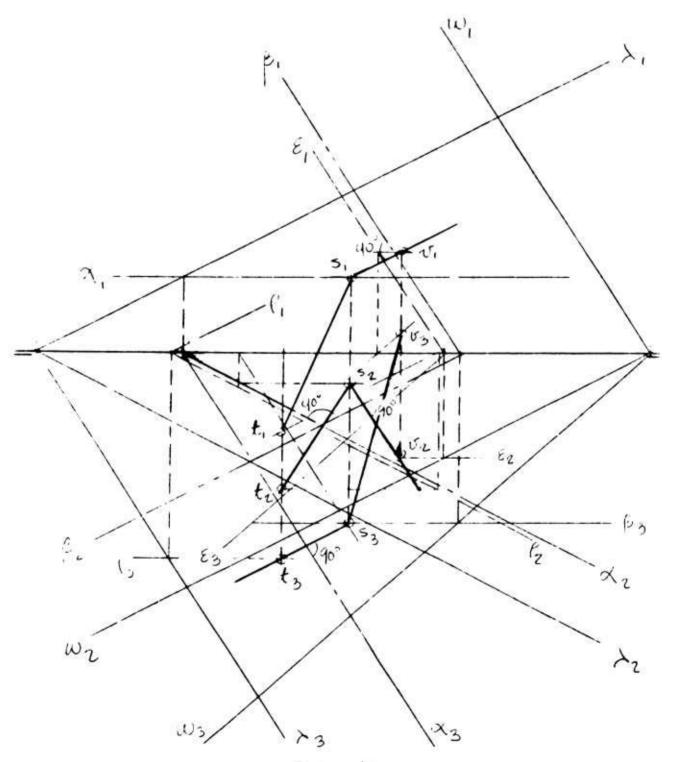


Figure 28

The first minimal angle is $\psi = 180^{\circ}$ - (tsv)

To determine the second angle, through (s) raise (sy) perpendicular to 3-D space Λ and (sx) perpendicular to 3-D space Λ . (Figure 24).

The second minimal angle is $\theta = 180^{\circ} - (xsy)$

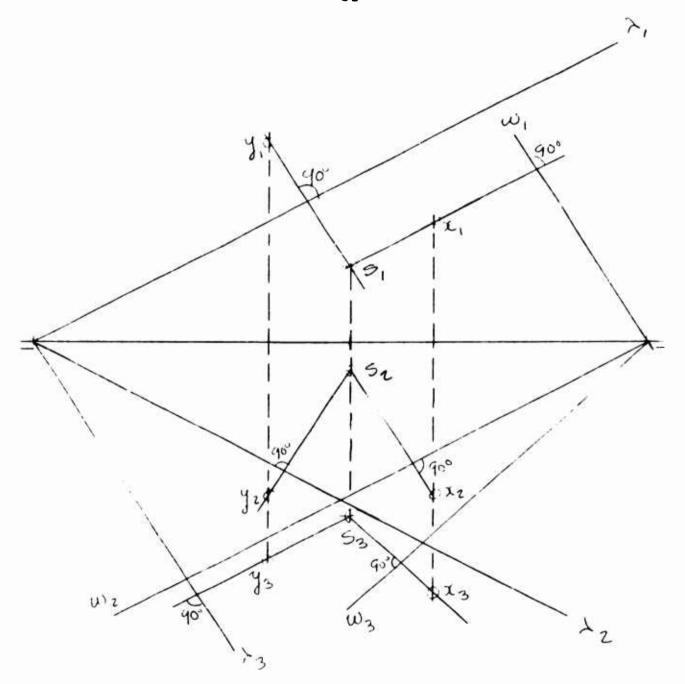


Figure 29

Problem No. 5

"To determine the true value of the angle between a line and a 3-D space".

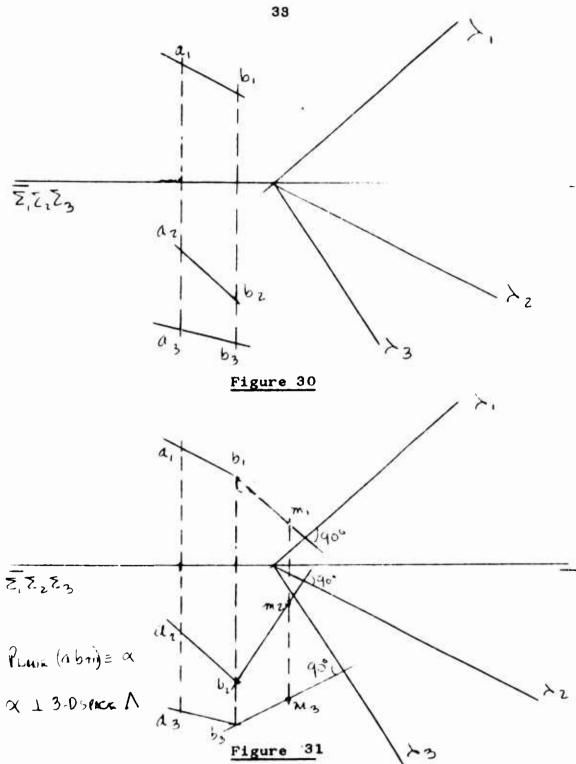
Solution

The angle of a lire and a 3-D space is equal to the angle between the line and its orthogonal projection on the 3-D space.

Given the line (ab) and the 3-D space \bigwedge (Figure 30), through (a) and (b) draw perpendiculars to \bigwedge . We have thus defined a plane \bigwedge , perpendicular to \bigwedge . (Figure 3).

To obtain the intersection of \propto and \wedge (which will be the projection of (ab) on \wedge), consider a 3-D space \top belonging to \propto - Figure 32. The intersection of \top and \wedge is a plane β . (Figure 33). The intersection of \propto and β is the projection (cd) of (ab) on \wedge . The two lines, (ab) and (cd) will be concurrent at a point (o), vertice of the angle. (Figures 34 and 35).





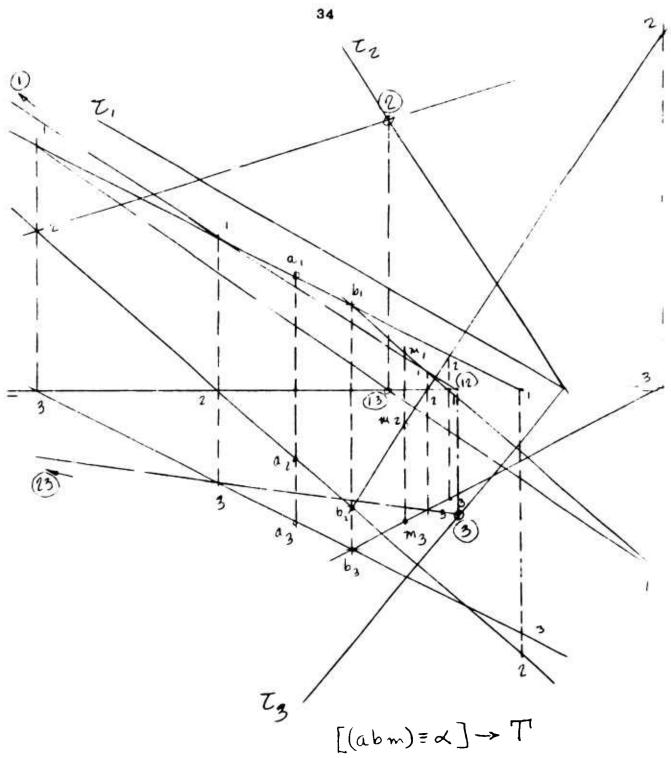


Figure 32

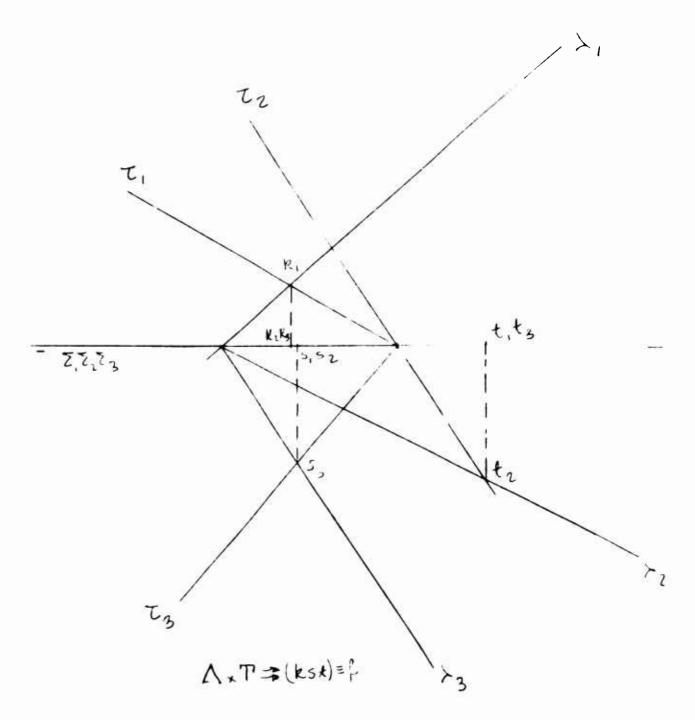


Figure 33

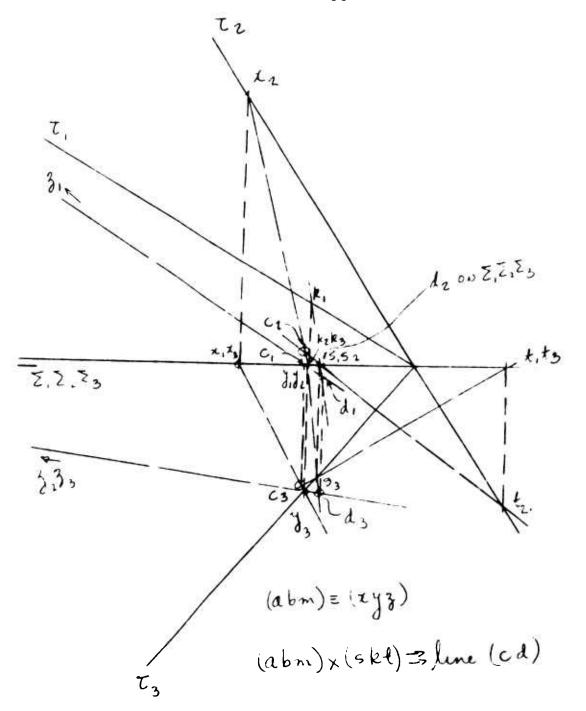


Figure 34

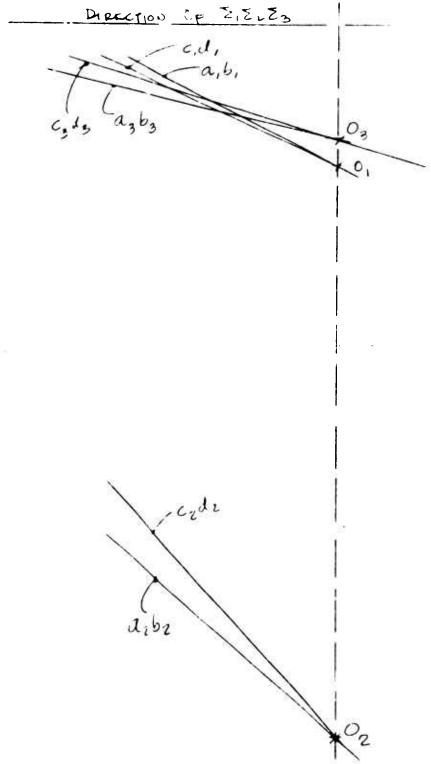


Figure 35

Problem No. 6

"To determine the angle of two 3-D spaces".

Solution

The plane angle which measures the angle of the two 3-D spaces has its vertice in the plane of intersection of the two 3-D spaces and its sides, one in each 3-D space, perpendicular to that plane of intersection.

Let \bigwedge and \bigwedge be the two given 3-D spaces. Their intersection is the plane (abc) $\leq \alpha$, on which we mark a point (o), to be vertice of a plane angle. (Figure 36).

To determine the projections of (os) of \bigwedge perpendicular to $\propto \Xi$ (abc) and (ot) of \bigwedge perpendicular to $\propto \Xi$ (abc) it will be necessary to apply a descriptive method with one of the following objectives:

- Obtain superimposition of and (by independent application of the method) with one of the 3-D spaces of the 4-D system of reference;
- Apply the method so that one of the 3-D spaces becomes parallel to a 3-D space \sum_{i} of the 4-D system of reference.

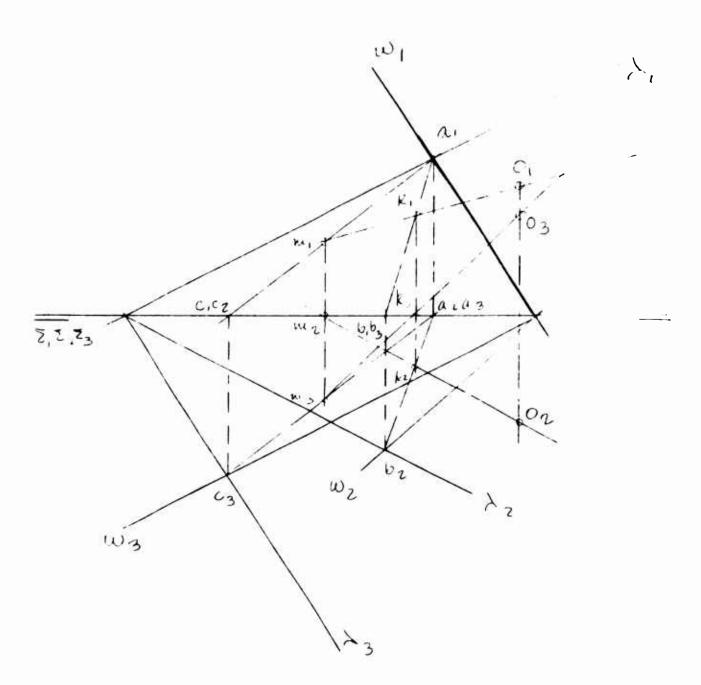


Figure 36

The result of the second alternative solution is shown in Figure 37. The 3-D space Ω is parallel to the 3-D space \sum_3 .

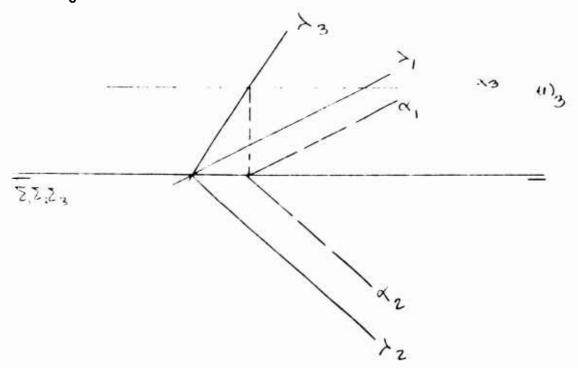


Figure 37

In Figure 38 we show the perpendicular (os) to \propto , in the 3-D space \triangle , and the perpendicular (ot) to \propto , in the 3-D space \triangle . The true value of the angle (tos)= φ may be obtained by applying the solution of Problem No. 1.

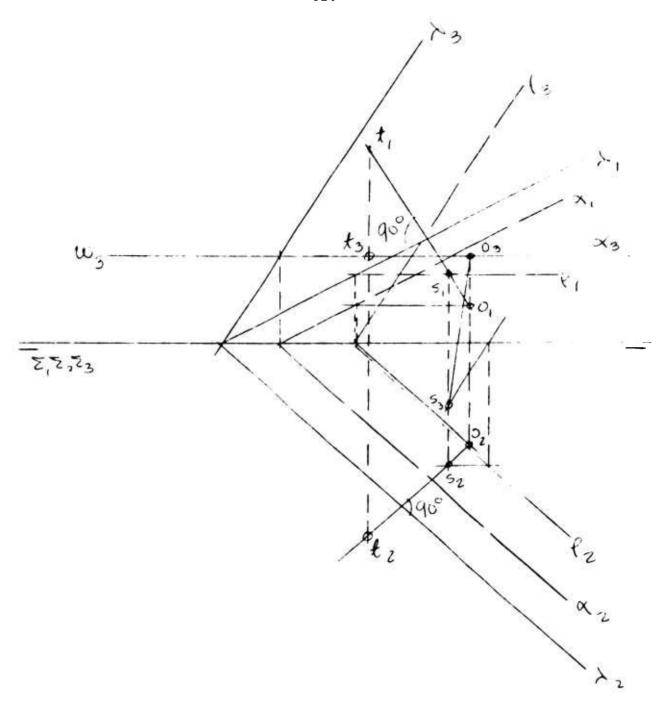


Figure 39

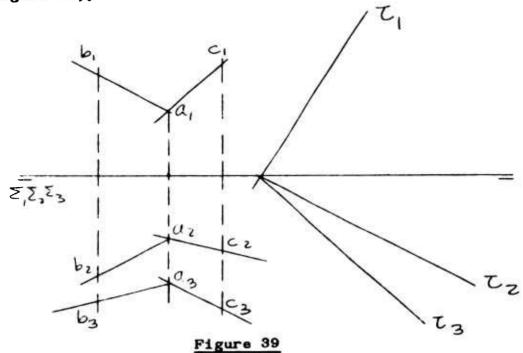
Problem No. 7

"To determine the true value of the angle between a plane and a 3-D space".

Solution

The angle that a plane makes with a 3-D space is the dihedral angle formed by the plane and the plane of intersection of a 3-D space belonging to the given plane and perpendicular to the given 3-D space.

Let (abc) be the given plane and \mathcal{T} the given space. (Figure 39).



To define a 3-D space Ω perpendicular to T, and belonging to (abc), through a point of the plane draw a perpendicular to T. The plane (abc) and the perpendicular determine Ω . (Figure 40).

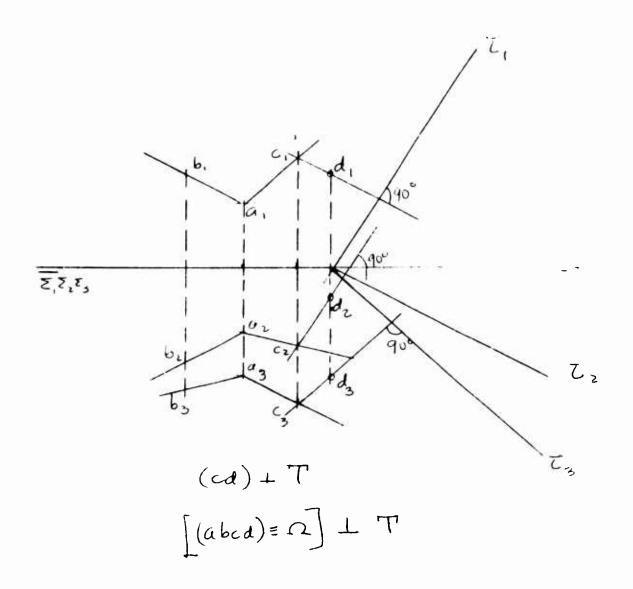


Figure 40

THE WILL

To complete the problem, proceed as follows:

- Determine the intersection of Ω and T , plane β .
- Determine the angle between planes \propto and β , concurrent along a line, since both belong to the same 3-D space, Ω .